

Tensor Multigrid

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Overview

- 1 Introduction
- 2 Tensor multigrid
- 3 Convergence analysis
- 4 Summary and extensions

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Model problem

Poisson's equation on the unit disc

$$\begin{aligned} -\Delta u(x) &= f(x) && \text{for all } x \in D := \{x \in \mathbb{R}^2 : \|x\| < 1\}, \\ u(x) &= 0 && \text{for all } x \in \partial D = \{x \in \mathbb{R}^2 : \|x\| = 1\}. \end{aligned}$$

Approach: Use angular coordinates

$$\Phi : [0, 1] \times [0, 2\pi] \rightarrow D, \quad \hat{x} = (r, \alpha) \mapsto \begin{pmatrix} r \sin(\alpha) \\ r \cos(\alpha) \end{pmatrix},$$



with $u \circ \Phi = \hat{u}$ and $f \circ \Phi = \hat{f}$ to obtain the equivalent equation

$$\begin{aligned} -\operatorname{div} \begin{pmatrix} r & \\ & 1/r \end{pmatrix} \operatorname{grad} \hat{u}(\hat{x}) &= r\hat{f}(\hat{x}) && \text{for all } \hat{x} \in \hat{D} := (0, 1) \times (0, 2\pi), \\ \hat{u}(\hat{x}) &= 0 && \text{for all } \hat{x} \in \partial\hat{D}. \end{aligned}$$

Challenge: Unbounded coefficients for $r \rightarrow 0$.

Variational formulation

Multiplication by test functions \hat{v} and partial integration yields

$$\underbrace{\int_{\hat{D}} \left\langle \begin{pmatrix} r \\ 1/r \end{pmatrix} \text{grad } \hat{v}(\hat{X}), \text{grad } \hat{u}(\hat{X}) \right\rangle d\hat{X}}_{=: a(\hat{v}, \hat{u})} = \underbrace{\int_{\hat{D}} r \hat{v}(\hat{X}) f(\hat{X}) d\hat{X}}_{=: f(\hat{v})}.$$

Bilinear form is

- symmetric,
- positive definite, but
- **not** H^1 -coercive.

Galerkin discretization: Choose hierarchy $V_0 \subseteq V_1 \subseteq V_2 \subseteq \dots$ of finite-dimensional subspaces and solve

$$a(\hat{v}_\ell, \hat{u}_\ell) = b(\hat{v}_\ell) \quad \text{for all } \hat{v}_\ell \in V_\ell.$$

Multigrid solver

Discretization leads to very large systems of linear equations.

→ Apply multigrid solver.

```
procedure MG( $\ell$ ,  $f_\ell$ , var  $u_\ell$ );  
begin  
  if  $\ell > 0$  begin  
     $d_\ell \leftarrow f_\ell - a(\cdot, u_\ell)$ ;  
    Find  $c_\ell \in V_\ell$  with  $w_\ell(v_\ell, c_\ell) = d_\ell(v_\ell)$  for all  $v_\ell \in V_\ell$ ;  
     $u_\ell \leftarrow u_\ell + c_\ell$ ;       $d_\ell \leftarrow f_\ell - a(\cdot, u_\ell)$ ;  
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    MG( $\ell - 1$ ,  $f_{\ell-1}$ ,  $u_{\ell-1}$ );  
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    Find  $u_0 \in V_0$  with  $a_0(v_0, u_0) = f_0(v_0)$  for all  $v_0 \in V_0$   
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Multigrid solver

Discretization leads to very large systems of linear equations.

→ Apply multigrid solver.

```
procedure  $MG(\ell, f_\ell, \text{var } u_\ell)$ ;  
begin  
  if  $\ell > 0$  begin  
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  end
```

Convergence

First experiment: Poisson problem on the unit square.

Level	1	2	3	4	5	6	7
Rate	0.100	0.153	0.167	0.168	0.170	0.170	0.170

Second experiment: Model problem with unbounded coefficients.

Level	1	2	3	4	5	6	7
Rate	0.301	0.685	0.903	0.974	0.994	0.998	0.999

Convergence

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Level	1	2	3	4	5	6	7
Rate	0.100	0.153	0.167	0.168	0.170	0.170	0.170

Second experiment: Model problem with unbounded coefficients.

Level	1	2	3	4	5	6	7
Rate	0.301	0.685	0.903	0.974	0.994	0.998	0.999

Third experiment: Model problem with tensor multigrid solver.

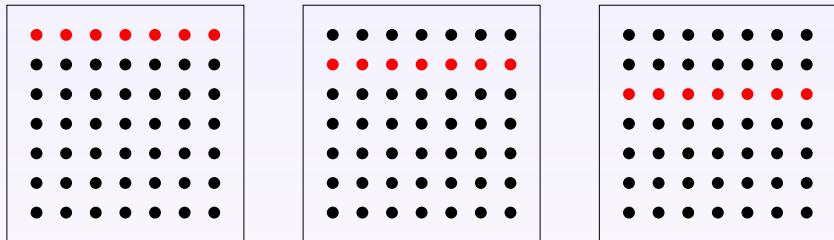
Level	1	2	3	4	5	6	7
Rate	0.175	0.197	0.198	0.199	0.199	0.200	0.200

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Block smoother

Idea: Treat rows of grid points simultaneously.

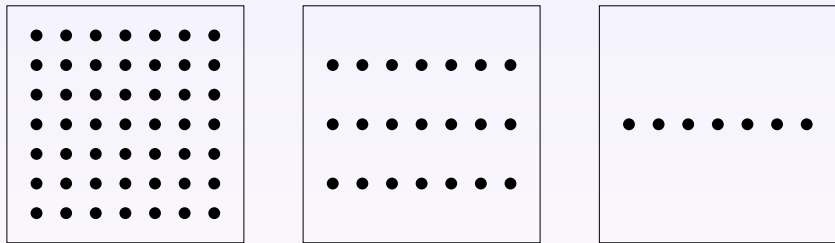


Implementation: Where the standard Jacobi and Gauß-Seidel iterations divide by the diagonal element, the block versions solve a tridiagonal system of equations.

→ Only moderately increased runtime.

Semicoarsened mesh hierarchy

Idea: Keep the mesh resolution fixed in r direction, apply coarsening only in α direction.



Advantage: No smoothing in r direction required.

Cost: 50% increase in grid points ($2n$ instead of $\frac{4}{3}n$).

Tensor spaces

We discretize by tensor spaces

$$V_\ell = V_r \otimes V_{\alpha,\ell} = \text{span}\{v_r \otimes v_\ell : v_r \in V_r, v_\ell \in V_{\alpha,\ell}\},$$

where $V_r \subseteq H_0^1[0, 1]$ and $V_{\alpha,0} \subseteq V_{\alpha,1} \subseteq V_{\alpha,2} \dots \subseteq H_0^1[0, 2\pi]$.

Bilinear form for tensor functions:

$$a(v_r \otimes v_\alpha, u_r \otimes u_\alpha) = a_r(v_r, u_r)m_\alpha(v_\alpha, u_\alpha) + m_r(v_r, u_r)a_\alpha(v_\alpha, u_\alpha)$$

with the one-dimensional bilinear forms

$$a_r(v_r, u_r) = \int_0^1 r v_r'(r) u_r'(r) dr, \quad m_r(v_r, u_r) = \int_0^1 \frac{1}{r} v_r(r) u_r(r) dr,$$
$$a_\alpha(v_\alpha, u_\alpha) = \int_0^{2\pi} v_\alpha'(\alpha) u_\alpha'(\alpha) d\alpha, \quad m_\alpha(v_\alpha, u_\alpha) = \int_0^{2\pi} v_\alpha(\alpha) u_\alpha(\alpha) d\alpha.$$

Tensor smoothers

Bilinear form satisfies

$$a(v_r \otimes v_\alpha, u_r \otimes u_\alpha) = a_r(v_r, u_r)m_\alpha(v_\alpha, u_\alpha) + m_r(v_r, u_r)a_\alpha(v_\alpha, u_\alpha).$$

Block smoothers are given by

$$w_\ell(v_r \otimes v_\alpha, u_r \otimes u_\alpha) = a_r(v_r, u_r)w_{m,\ell}(v_\alpha, u_\alpha) + m_r(v_r, u_r)w_{a,\ell}(v_\alpha, u_\alpha),$$

where $w_{m,\ell}$ and $w_{a,\ell}$ correspond to one-dimensional smoothers for the bilinear forms m_α and a_α , respectively.

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General multigrid theory

If we can prove the **smoothing property**

$$a(v_\ell, v_\ell) \leq w_\ell(v_\ell, v_\ell) \quad \text{for all } v_\ell \in V_\ell$$

and the **approximation property**

$$w_\ell(v_\ell, v_\ell) \leq C_A a(v_\ell, v_\ell) \quad \text{for all } v_\ell \in V_\ell \text{ with } a(v_\ell, V_{\ell-1}) = 0,$$

the convergence rate of the multigrid solver is bounded by

$$\rho \leq \frac{C_A}{C_A + 2}.$$

☞ D. N. Arnold, R. S. Falk, R. Winther: Preconditioning in $H(\text{div})$ and applications, Math. Comp. 66(219):957–984 (1997)

Eigenvector basis

Approach: For tensor functions, we have

$$\begin{aligned} \mathbf{a}(\mathbf{v}_r \otimes \mathbf{v}_\alpha, \mathbf{v}_r \otimes \mathbf{v}_\alpha) &= \mathbf{a}_r(\mathbf{v}_r, \mathbf{v}_r) \mathbf{m}_\alpha(\mathbf{v}_\alpha, \mathbf{v}_\alpha) + m_r(\mathbf{v}_r, \mathbf{v}_r) \mathbf{a}_\alpha(\mathbf{v}_\alpha, \mathbf{v}_\alpha) \\ \mathbf{w}_\ell(\mathbf{v}_r \otimes \mathbf{v}_\alpha, \mathbf{v}_r \otimes \mathbf{v}_\alpha) &= \mathbf{a}_r(\mathbf{v}_r, \mathbf{v}_r) \mathbf{w}_{m,\ell}(\mathbf{v}_\alpha, \mathbf{v}_\alpha) + m_r(\mathbf{v}_r, \mathbf{v}_r) \mathbf{w}_{a,\ell}(\mathbf{v}_\alpha, \mathbf{v}_\alpha) \end{aligned}$$

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Idea: Use m_r -orthonormal eigenvector basis $(\mathbf{e}_\nu)_{\nu \in \mathcal{I}}$ given by

$$\mathbf{a}_r(\mathbf{e}_\nu, \mathbf{e}_\mu) = \lambda_\nu \delta_{\nu\mu}, \quad \mathbf{m}_r(\mathbf{e}_\nu, \mathbf{e}_\mu) = \delta_{\nu\mu} \quad \text{for all } \nu, \mu \in \mathcal{I}.$$

Result: For each $\mathbf{v}_\ell \in V_\ell$, we can find $(\mathbf{v}_\nu)_{\nu \in \mathcal{I}}$ such that

$$\begin{aligned}\mathbf{v}_\ell &= \sum_{\nu \in \mathcal{I}} \mathbf{e}_\nu \otimes \mathbf{v}_\nu, & \mathbf{a}(\mathbf{v}_\ell, \mathbf{v}_\ell) &= \sum_{\nu \in \mathcal{I}} \lambda_\nu \mathbf{m}_\alpha(\mathbf{v}_\alpha, \mathbf{v}_\alpha) + \mathbf{a}_\alpha(\mathbf{v}_\alpha, \mathbf{v}_\alpha), \\ & & \mathbf{w}_\ell(\mathbf{v}_\ell, \mathbf{v}_\ell) &= \sum_{\nu \in \mathcal{I}} \lambda_\nu \mathbf{w}_{m,\ell}(\mathbf{v}_\alpha, \mathbf{v}_\alpha) + \mathbf{w}_{a,\ell}(\mathbf{v}_\alpha, \mathbf{v}_\alpha).\end{aligned}$$

Smoothing property

Let $v_\ell \in V_\ell$. Let $(v_\nu)_{\nu \in \mathcal{I}}$ be such that

$$v_\ell = \sum_{\nu \in \mathcal{I}} e_\nu \otimes v_\nu.$$

Since a_α and m_α are well-behaved, we can prove

$$m_\alpha(v_\alpha, v_\alpha) \leq w_{m,\alpha}(v_\alpha, v_\alpha), \quad a_\alpha(v_\alpha, v_\alpha) \leq w_{a,\alpha}(v_\alpha, v_\alpha).$$

Result: Using the eigenvector expansion, this implies

$$\begin{aligned} a(v_\ell, v_\ell) &= \sum_{\nu \in \mathcal{I}} \lambda_\nu m_\alpha(v_\nu, v_\nu) + a_\alpha(v_\nu, v_\nu) \\ &\leq \sum_{\nu \in \mathcal{I}} \lambda_\nu w_{m,\alpha}(v_\nu, v_\nu) + w_{a,\alpha}(v_\nu, v_\nu) = w_\ell(v_\ell, v_\ell). \end{aligned}$$

Approximation property

Let $v_\ell \in V_\ell$ with $a(v_\ell, V_{\ell-1}) = 0$, let $(v_\nu)_{\nu \in \mathcal{I}}$ be as before.

Semicoarsening: $e_\nu \otimes u_{\ell-1} \in V_{\ell-1}$ for all $u_{\ell-1} \in V_{\alpha, \ell-1}$, so we get

$$\begin{aligned} 0 &= a(v_\ell, e_\nu \otimes u_{\ell-1}) \\ &= \lambda_\nu m_\alpha(v_\nu, u_{\ell-1}) + a_\alpha(v_\nu, u_{\ell-1}) \quad \text{for all } \nu \in \mathcal{I}, u_{\ell-1} \in V_{\alpha, \ell-1}. \end{aligned}$$

Standard multigrid theory can be applied to prove

$$\lambda_\nu w_{m, \alpha}(v_\nu, v_\nu) + w_{a, \alpha}(v_\nu, v_\nu) \leq C_A (\lambda_\nu m_\alpha(v_\nu, v_\nu) + a_\alpha(v_\nu, v_\nu))$$

with an independent constant C_A (Fourier: $C_A = 4$ for model problem).

Using the eigenvalue decomposition again, we find

$$w_\ell(v_\ell, v_\ell) \leq C_A a(v_\ell, v_\ell).$$

Robustness

Goal: Investigate performance for problems of the form

$$-\operatorname{div} \begin{pmatrix} \sigma(x) \\ \tau(x) \end{pmatrix} \operatorname{grad} u(x, y) = f(x, y).$$

σ	τ	5	6	7	8	9	10	
1	1	0.35	0.35	0.35	0.35	0.35	0.35	Jacobi
x	$1/x$	0.40	0.40	0.40	0.39	0.36	0.35	
10^8	1	0.56	0.56	0.56	0.56	0.56	0.56	
10^{-8}	1	0.40	0.40	0.40	0.40	0.40	0.40	
1	1	0.09	0.09	0.09	0.09	0.09	0.09	Gauß-Seidel
x	$1/x$	0.09	0.09	0.09	0.09	0.09	0.09	
10^8	1	0.09	0.09	0.09	0.09	0.09	0.09	
10^{-8}	1	0.00	0.00	0.00	0.00	0.00	0.01	

Result: Very robust, particularly with red-black Gauß-Seidel.

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Summary

Tensor multigrid: Use **block smoothing** and **semicoarsening** to hide the effects of unbounded coefficients.

Convergence proof: Use eigenvector basis to reduce to family of standard problems that can be treated by standard theory.

Requirements: Both method and proof work for all problems of the form

$$-\operatorname{div} \begin{pmatrix} \sigma(x) & \\ & \tau(x) \end{pmatrix} \operatorname{grad} u(x, y) = f(x, y) \quad \text{for all } x \in D_x, y \in D_y$$

as long as $\sigma, \tau > 0$ almost everywhere.

Generalization

Maxwell's equations lead to

$$\operatorname{curl}^* \mu(x) \operatorname{curl} u(x, y) + \tau(x)u(x, y) = f(x, y) \quad \text{for all } x \in D_x, y \in D_y.$$

We consider again the case that $\mu, \tau > 0$ are unbounded.

Discretization: Nédélec's edge basis functions on a tensor grid.

Approach: Use **representation operator**

$$R_{e,\epsilon} : H_0^1(D_y) \rightarrow H_0(\operatorname{curl}, D), \quad v \mapsto \begin{pmatrix} \epsilon \otimes v \\ 0 \end{pmatrix} + \operatorname{grad}(e \otimes v),$$

with $e \in H_0^1(D_x)$, $\epsilon \in L^2(D_x)$.

Eigenvector decomposition can be constructed by solving a coupled eigenvector problem involving e and ϵ .

→ Reduction to one-dimensional Poisson problems.